

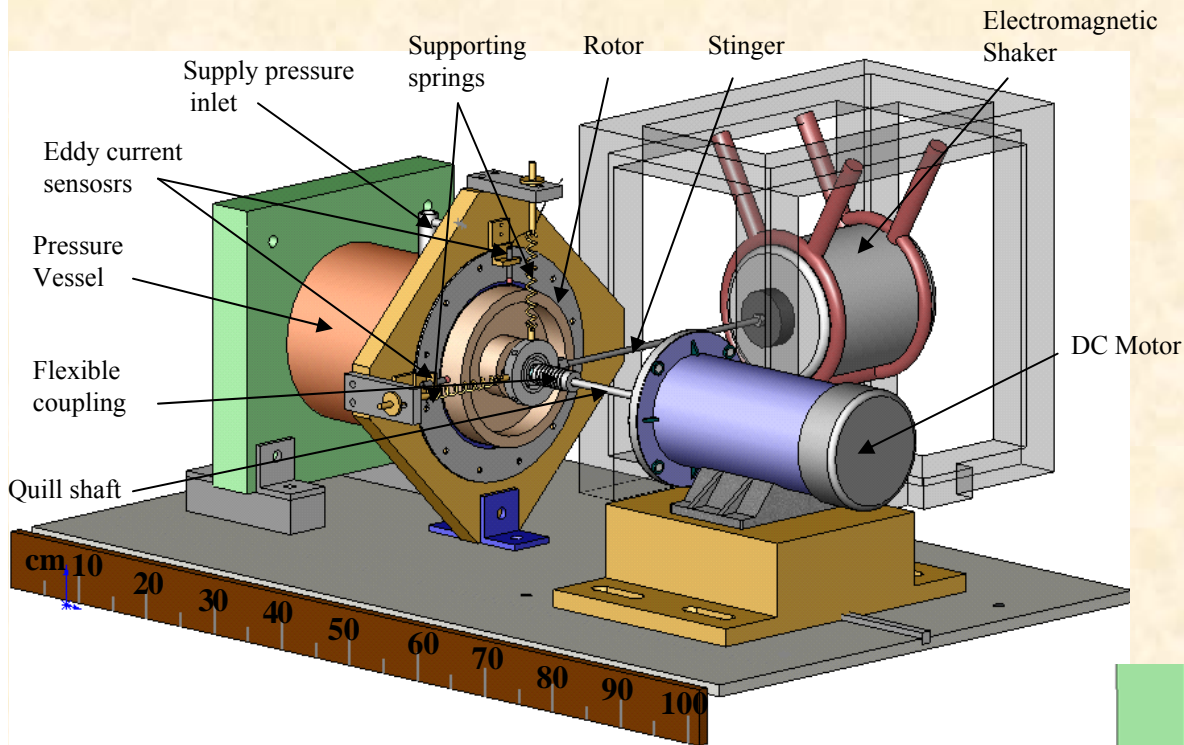
MEEN 617 - April 2008

**An example of system
parameter identification
(Hybrid Brush Seal)**

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**Thanks to Adolfo Delgado, José Baker (RAs) &
support from Siemens Power Generation**

Experimental Facility



Test Rig: Rotordynamic Configuration

Structural parameters

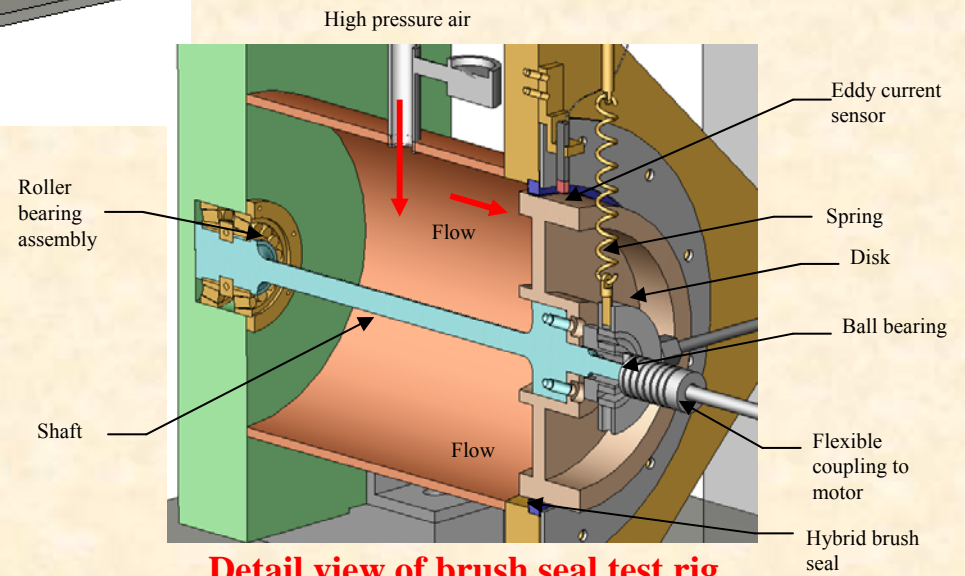
$$K_{\text{shaft}} = 243 \text{ lbf/in (42.5 kN/m)}$$

$$M_{\text{s+d}} = 9.8 \text{ lb (4.45 kg)}$$

$$\zeta: 0.01 \% \text{ (damping ratio)}$$

Installation:

6.550" diameter brush seal
 Max. air Pressure: 60 psig
 Shaker (20 lb max)



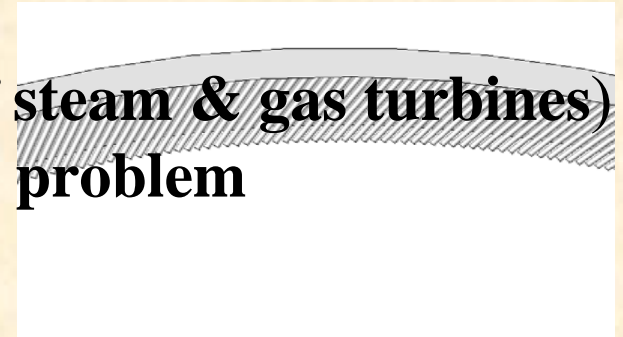
Detail view of brush seal test rig

Brush Seals

Reduce secondary leakage in turbomachinery

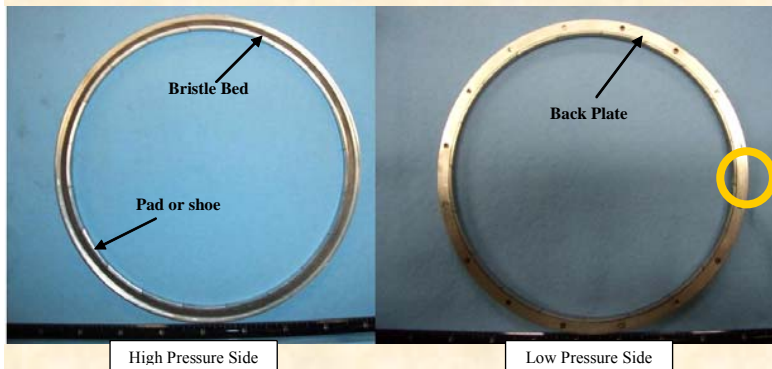
Replace labyrinth seals in HP TM (hot side of steam & gas turbines)

Wear and thermal distortions are a reliability problem



Hybrid Brush Seals

Novel improvement over BS. Reduce more leakage and do not introduce wear or thermal distortion. Allow bi-directional rotation

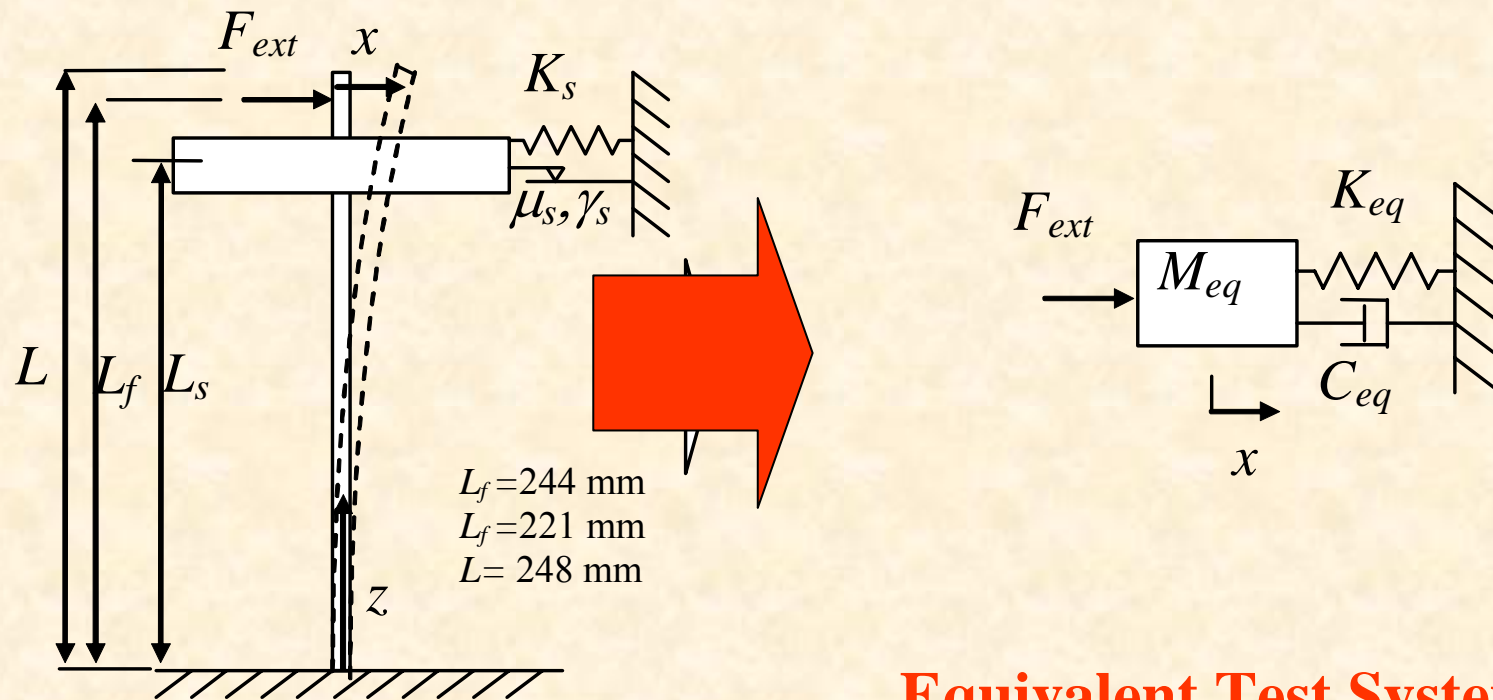


* Close-up courtesy of Advanced Technologies Group, Inc.

Spring Lever Mechanism

Courtesy of Advanced Turbomachinery Group®

Dynamic Load Tests (no shaft rotation)



$$M_{eq} \ddot{x} + K_{eq} x + C_{eq} \dot{x} = F_{ext}$$

Parameter Identification (no shaft rotation)

ASME DETC2005-84159

$$\bar{x} = x e^{i\omega t}$$

$$\bar{F} = F_{ext} e^{i\omega t}$$

← Harmonic force
& displacements

$$Z = \frac{\bar{F}}{\bar{x}} = (K_{eq} - \omega^2 M_{eq}) + i \omega C_{eq}$$

← Impedance Function

$$W = \oint F_{ext} \dot{x} dt$$

← Work External

$$E_{dis} = \pi \omega C_{eq} |\bar{x}|^2$$

← Viscous Dissipation

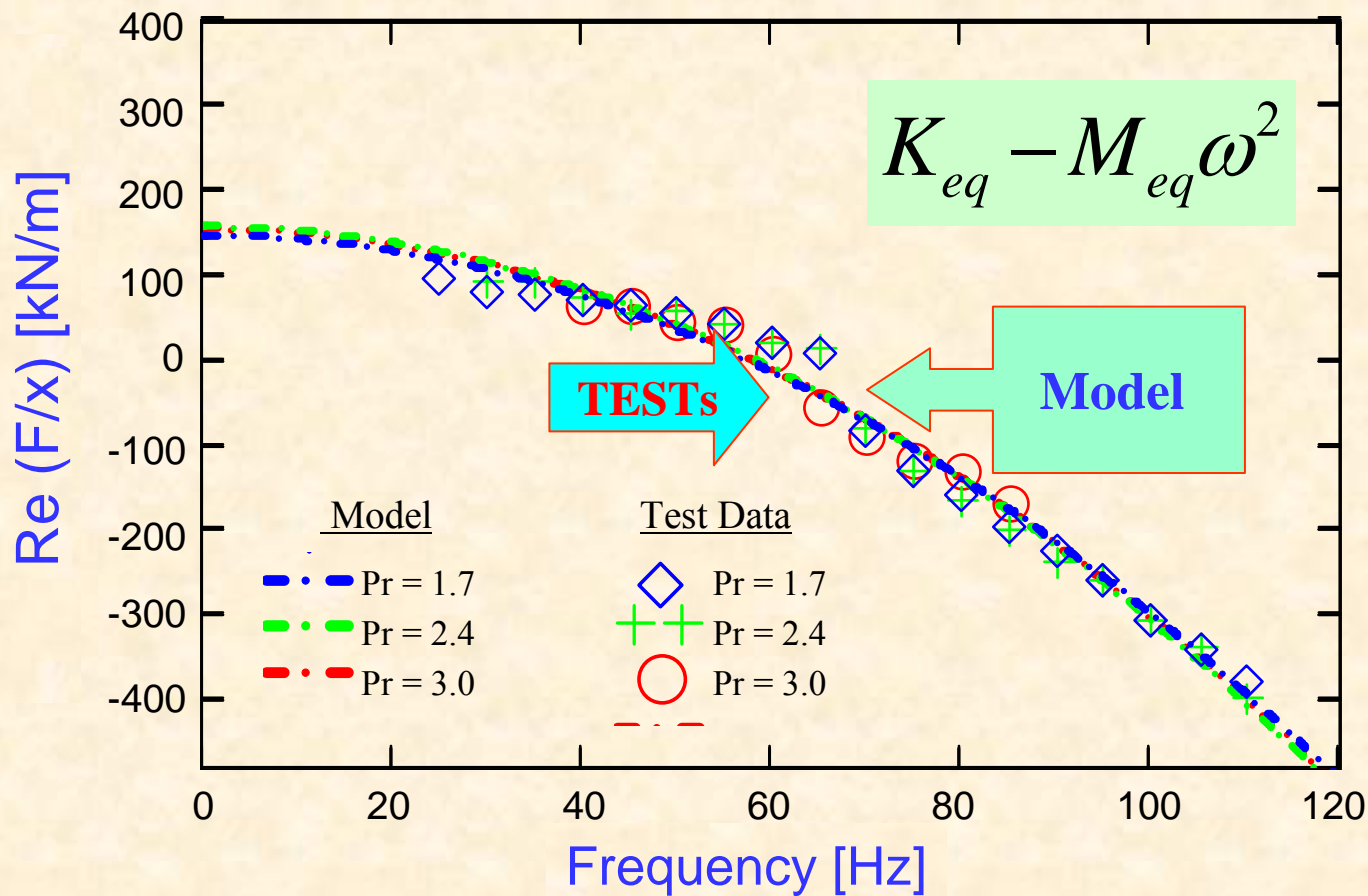
$$E_{dis} = \gamma_{eq} \pi K_{eq} |\bar{x}|^2 + 4 \mu |\bar{F}| |\bar{x}|$$

← **DRY
FRICTION &
STRUCTURAL
DAMPING**

HBS Dynamic Stiffness vs. Frequency (no shaft rotation)

Load = 63 N, frequency: 20-100Hz

Pressure ratio ($P_r = P_s/P_d$) = Discharge/Supply

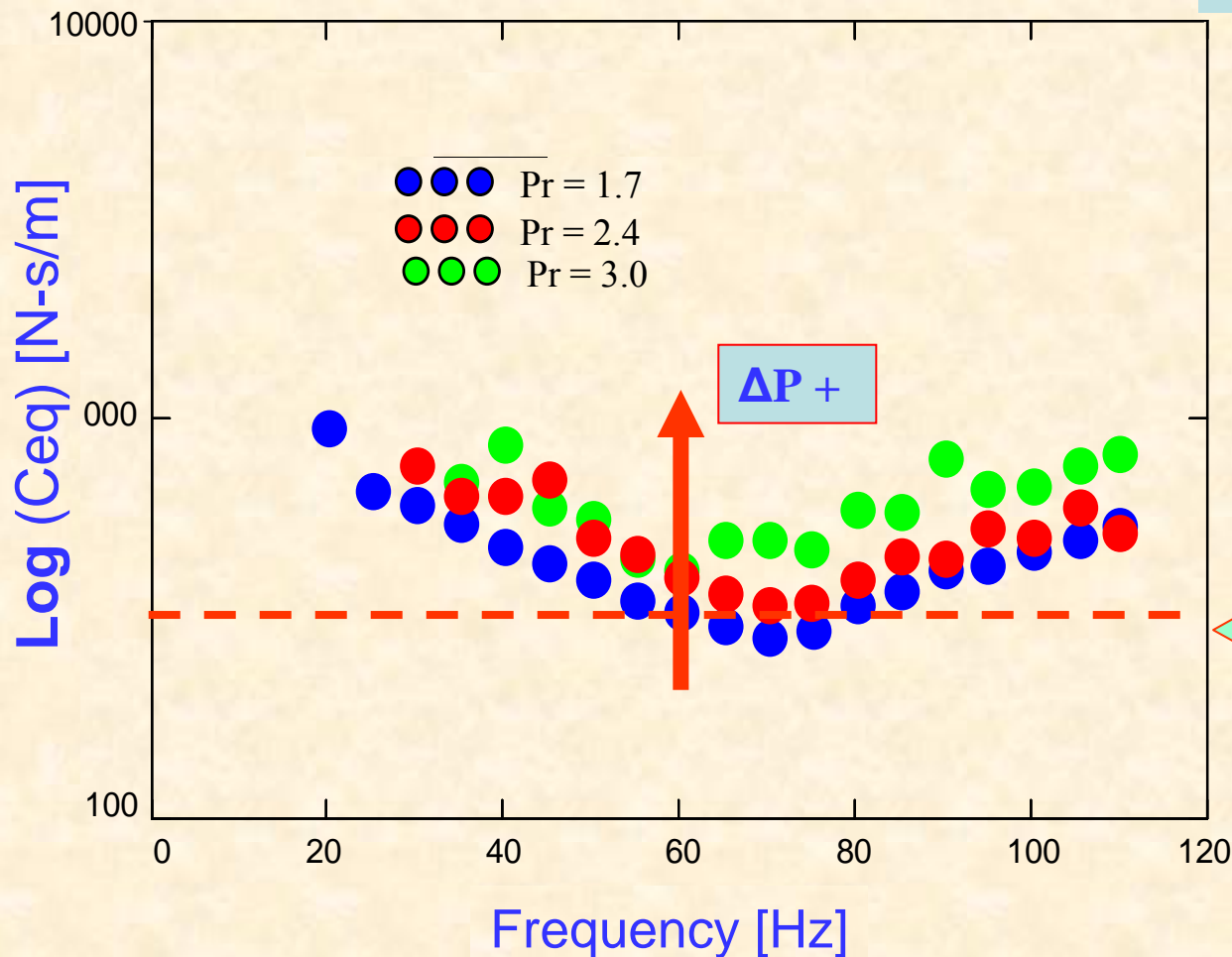


HBS Equivalent Viscous Damping vs. Frequency (no shaft rotation)

Load = 63 N, frequency 20-110Hz

Pressure ratio ($P_r = P_s/P_d$) = Discharge/Supply

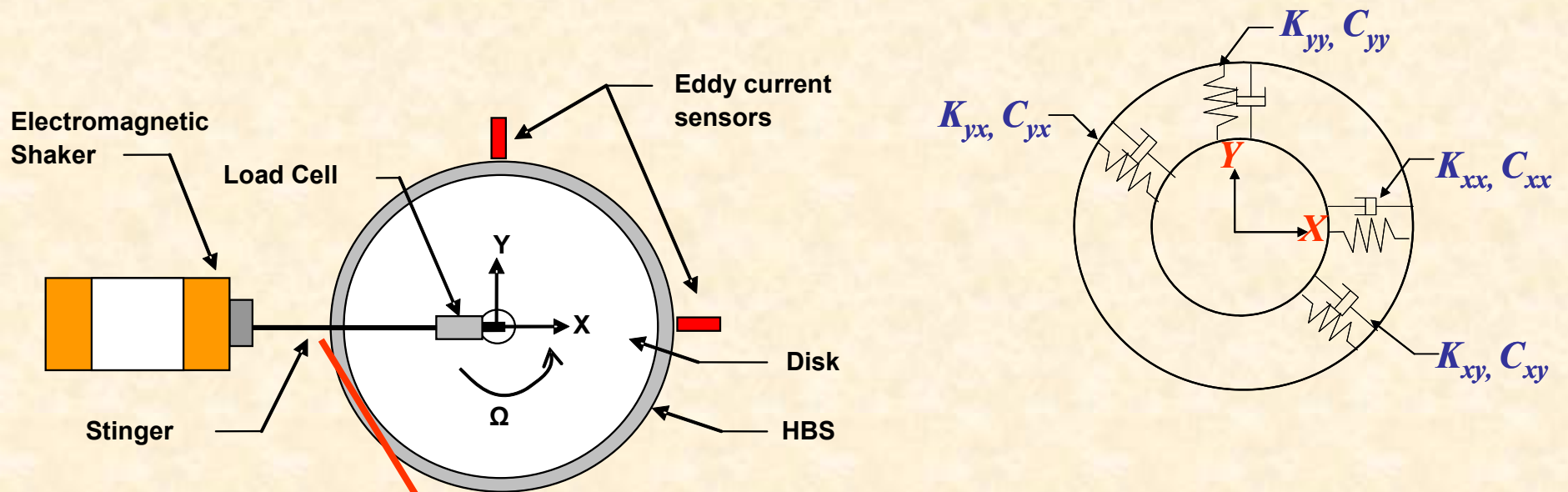
$$C_{eq} = \frac{\gamma_{eq} K_{eq}}{\omega} + \frac{4\mu|\bar{F}|}{\pi\omega|\bar{x}|}$$



Equivalent damping increases slightly with pressure differential. Results typical of a system with dry-friction & material damping energy dissipation

Viscous Model

Identification of Rotordynamic Force Coefficients



Excitation force
(frequency ω)

$$\begin{bmatrix} M_{xx} & M_{xy} \\ M_{yx} & M_{yy} \end{bmatrix} \begin{Bmatrix} \ddot{x} \\ \ddot{y} \end{Bmatrix} + \begin{bmatrix} K_{xx} & K_{xy} \\ K_{yx} & K_{yy} \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} + \begin{bmatrix} C_{xx} & C_{xy} \\ C_{yx} & C_{yy} \end{bmatrix} \begin{Bmatrix} \dot{x} \\ \dot{y} \end{Bmatrix} = \begin{pmatrix} F_x \\ 0 \end{pmatrix} + \begin{pmatrix} F_{ix} \\ F_{iy} \end{pmatrix}$$

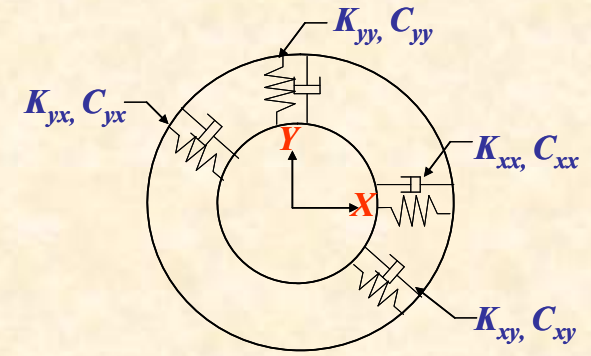
Imbalance forces ($1X=\Omega$)

Identification of Rotordynamic Force Coefficients

For periodic force excitation:

$$\bar{F}_x = F_x e^{i\omega t} \quad \rightarrow \quad \bar{y} = ye^{i\omega t}$$

$$\bar{x} = xe^{i\omega t}$$



EOMS reduce to:

$$Z_{xx} \cdot \bar{x} + Z_{xy} \cdot \bar{y} = \bar{F}_x$$

$$Z_{yx} \cdot \bar{x} + Z_{yy} \cdot \bar{y} = 0$$

With impedances:

$$Z_{\alpha\beta} = \left\{ K_{\alpha\beta} - M_{\alpha\beta} \omega^2 + iC_{\alpha\beta} \omega \right\}, \alpha\beta=x,y$$

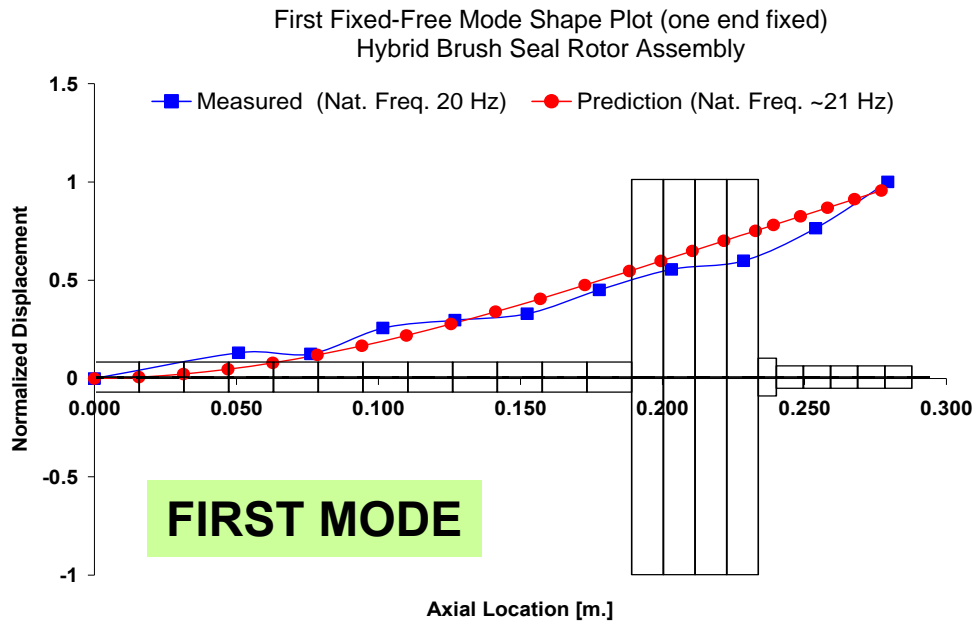
For centered operation
(axi-symmetry)

$$Z_{xx} = Z_{yy}$$

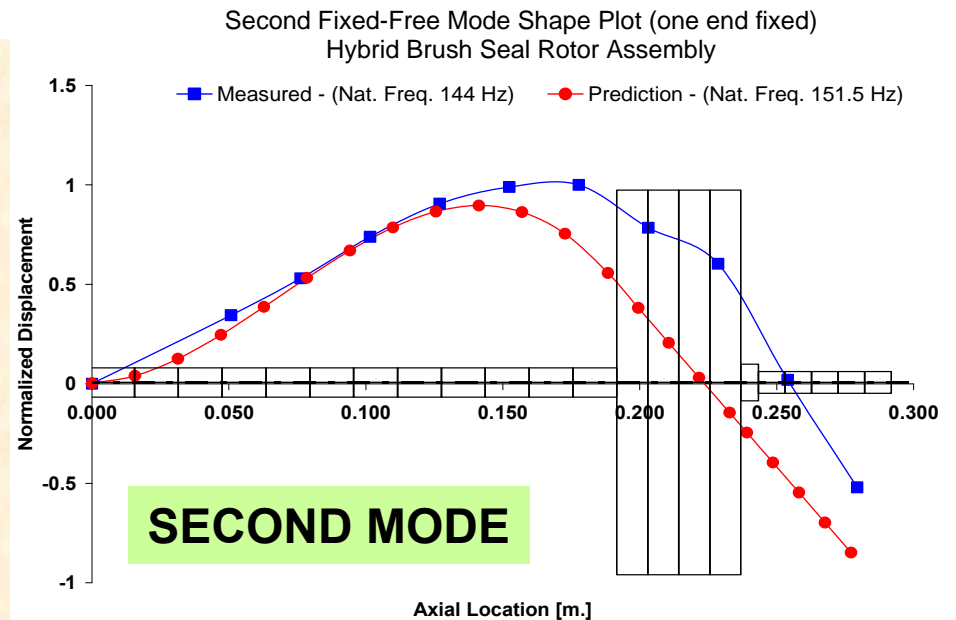
$$Z_{xy} = -Z_{yx}$$

$$\begin{bmatrix} M_{xx} & 0 \\ 0 & M_{xx} \end{bmatrix} \begin{Bmatrix} \ddot{x} \\ \ddot{y} \end{Bmatrix} + \begin{bmatrix} K_{xx} & K_{xy} \\ -K_{xy} & K_{xx} \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix} + \begin{bmatrix} C_{xx} & 0 \\ 0 & C_{xx} \end{bmatrix} \begin{Bmatrix} \dot{x} \\ \dot{y} \end{Bmatrix} = \begin{pmatrix} F_x \\ 0 \end{pmatrix}$$

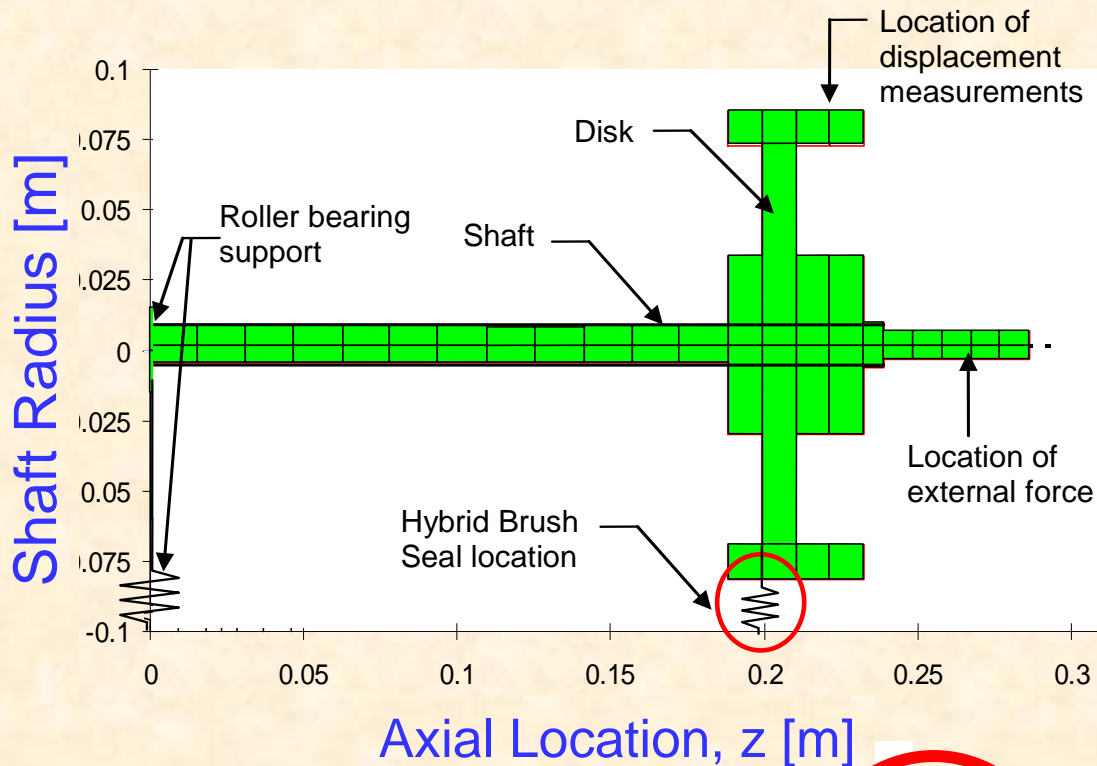
Rotor mode shapes



Only first mode excited
in rotor speed range (0-
1200 rpm)



Effect of rotor speed on rotor-HBS natural frequency



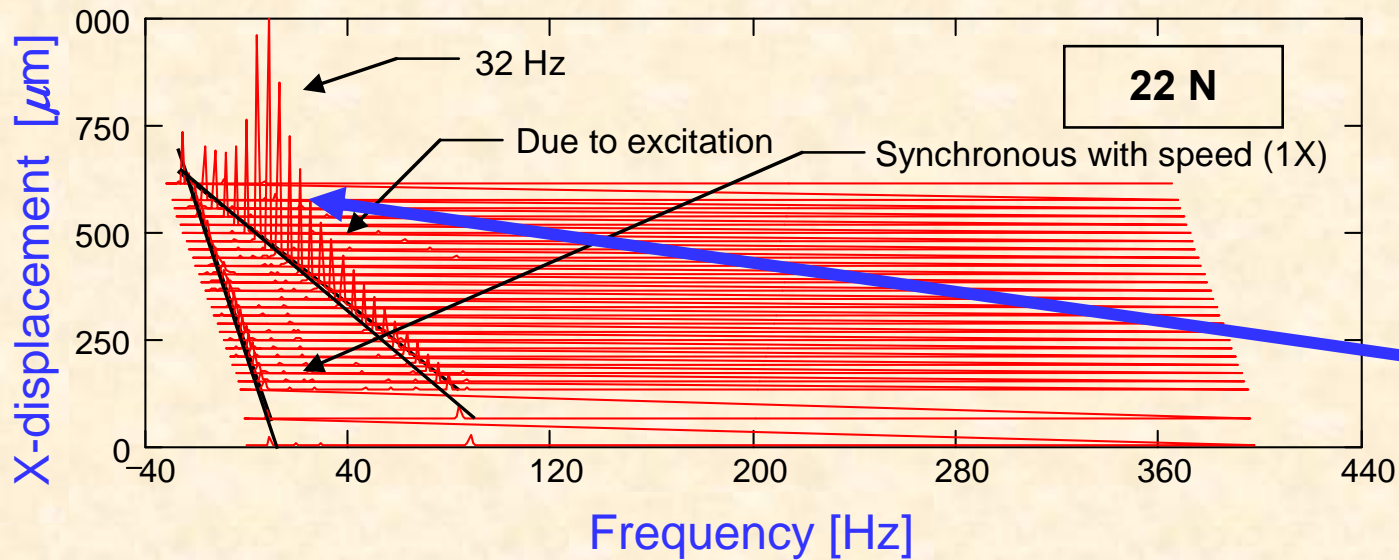
Gyroscopic effects negligible for test rotor speeds (600 and 1,200 rpm [20 Hz])

Rotor Speed [RPM]	1 st Backward Nat. Frequency, [Hz]	1 st Forward Nat. Frequency, [Hz]	2 nd Forward Nat. Frequency, [Hz]	3 rd Forward Nat. Frequency, [Hz]
0	30.5	30.5	146	1351
600	29.7	31.4	154	1351
1200	28.8	32.2	163	1351

T=32 Hz

CROSS-Coupling Effects under rotation

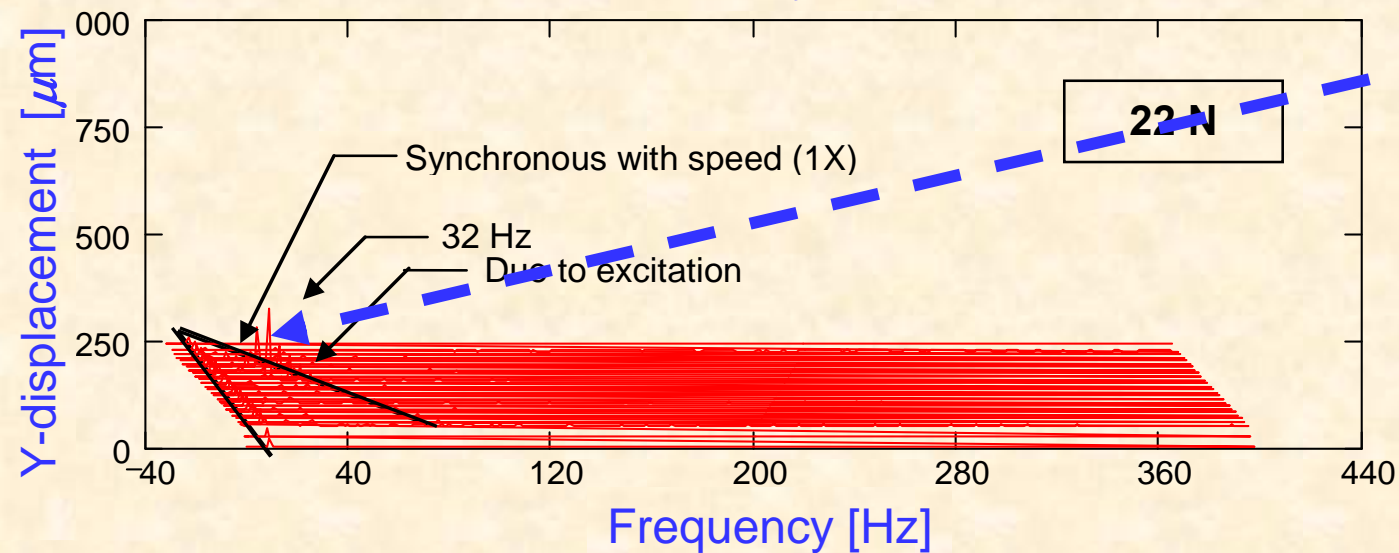
Load=22 N, 600 rpm



For load along X direction,
rotor principal (X) motions



cross (Y) motions



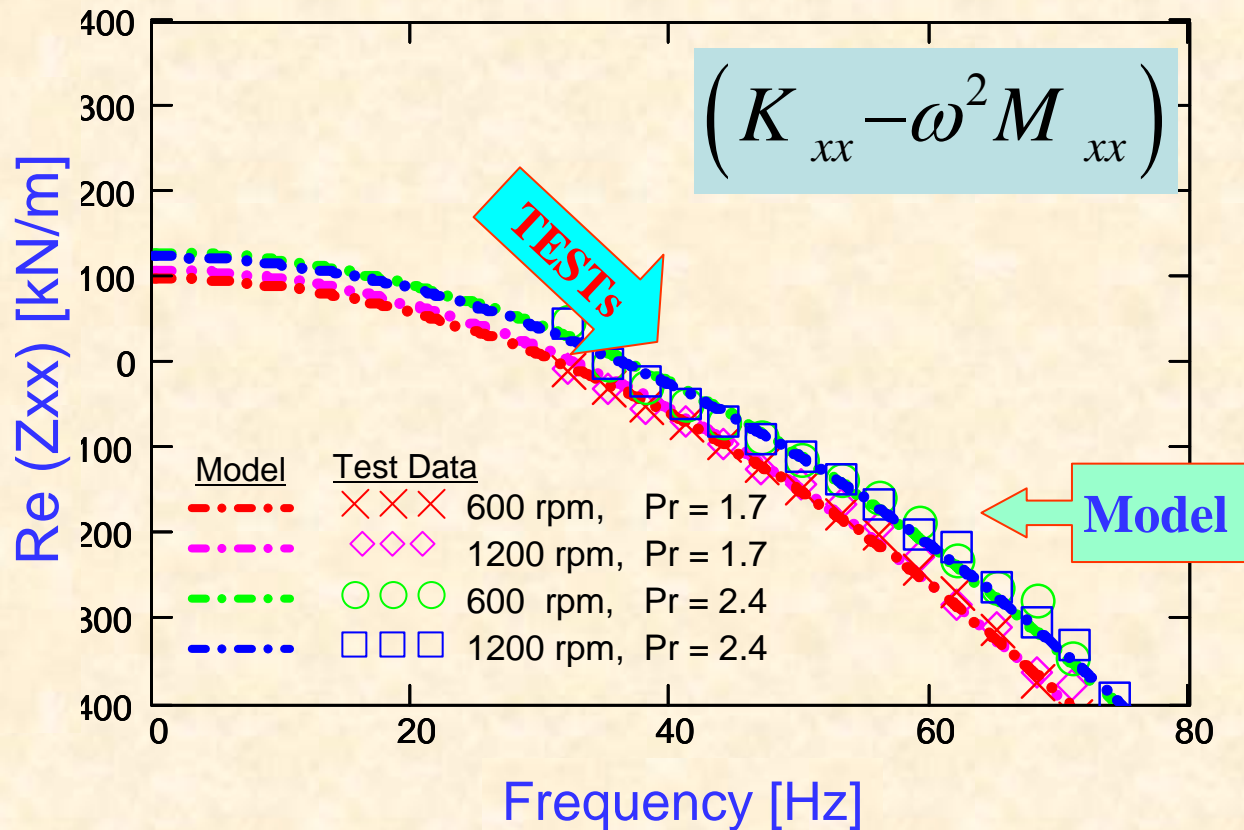
3X motions
always small

Test dynamic stiffness vs. frequency

Load = 22 N, frequency 25-80Hz

Pressure ratio ($P_r = P_s/P_d$) = Discharge/Supply

$$Z_{xx} = \frac{\bar{F}_x \cdot \bar{x}}{(\bar{x}^2 + \bar{y}^2)}$$



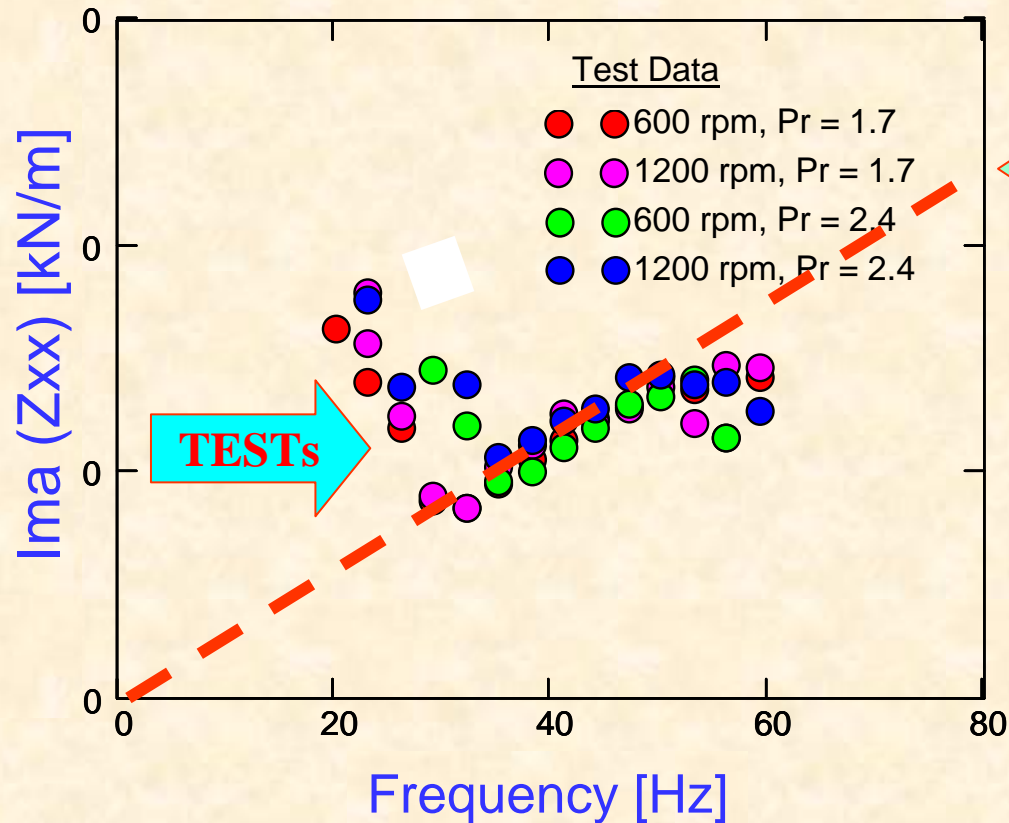
Model reproduces the measured real part of impedance.
Little effect of pressurization

Test impedance (imag) vs. frequency

Load = 22 N, frequency 25-80Hz

Pressure ratio ($P_r = P_s/P_d$) = Discharge/Supply

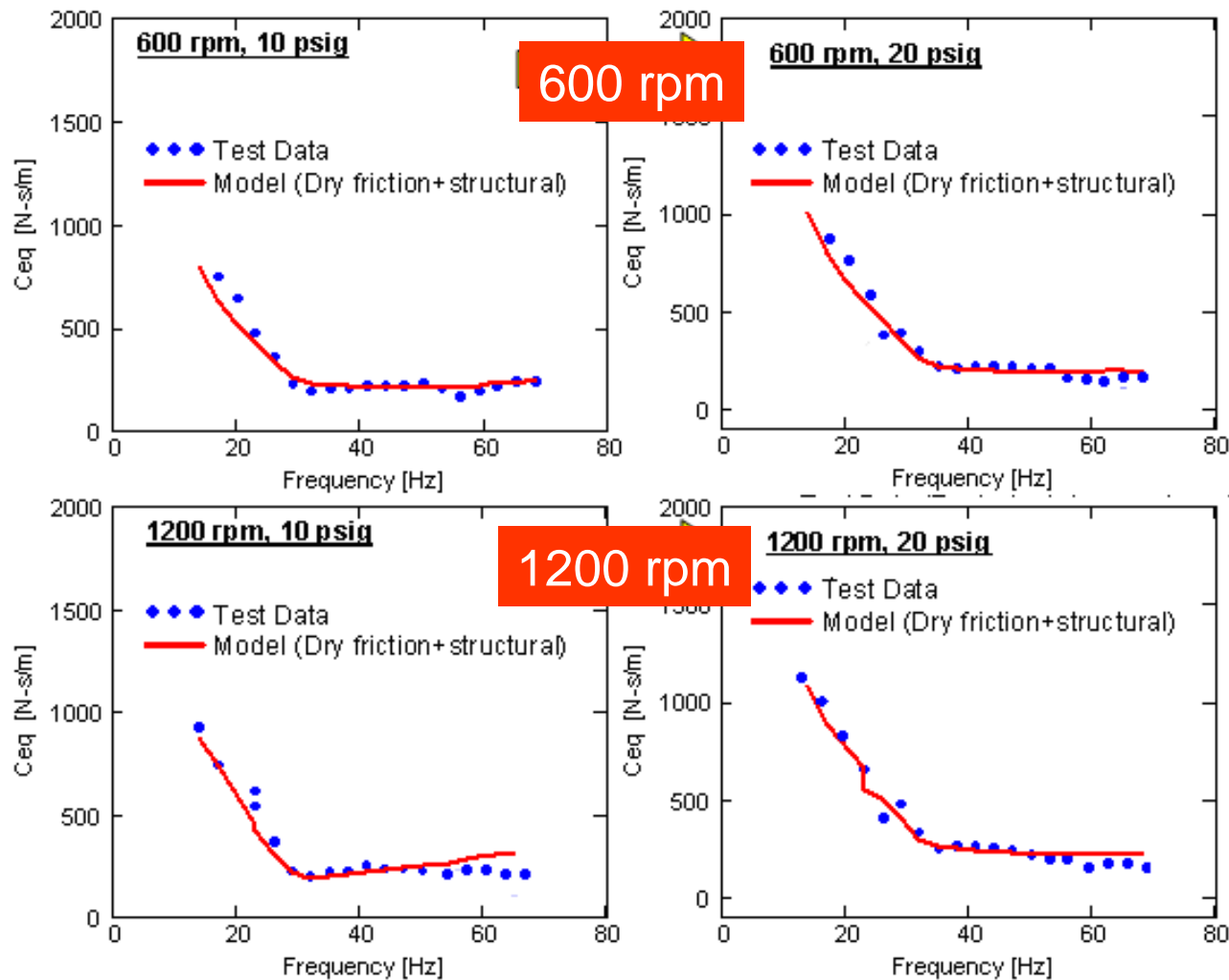
$$Z_{yx} = -Z_{yy} \frac{\bar{y}}{\bar{x}}$$



Viscous Model

Damping is
NOT viscous

Equivalent Viscous Damping ($C_{xx} \sim C_{eq}$) vs. Frequency



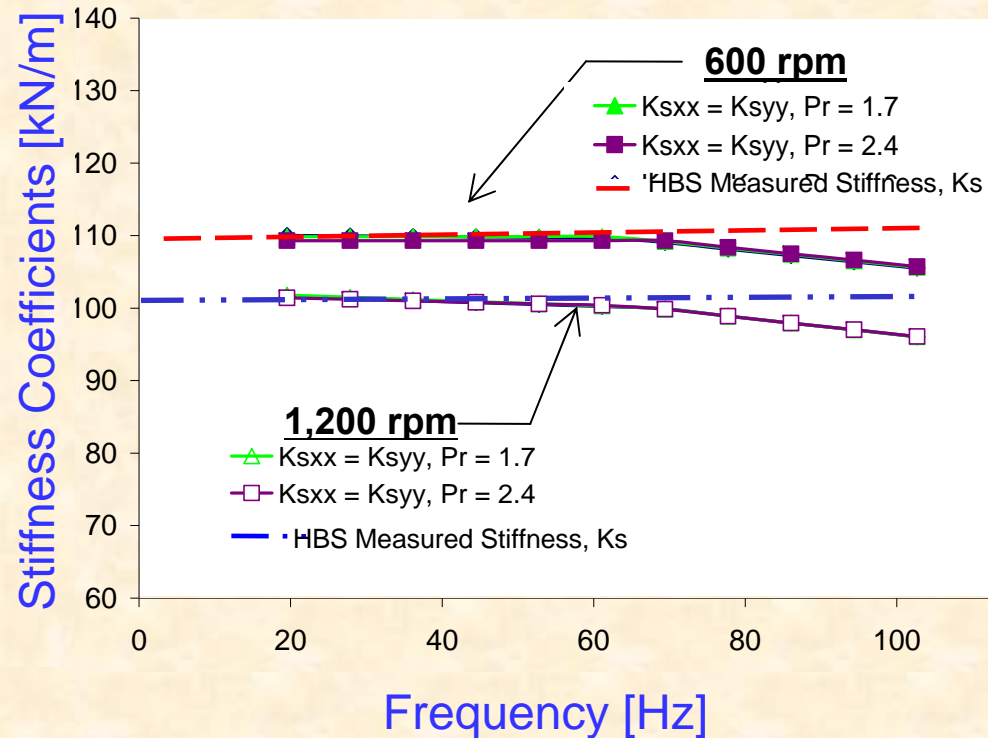
Damping decreases with frequency, with little effect of supply pressure. Minimum value at test system natural frequency (~32 Hz)

$Pr=1.7$

$Pr=2.4$

HBS predicted & test direct stiffness vs. frequency

Frequency 25-100 Hz

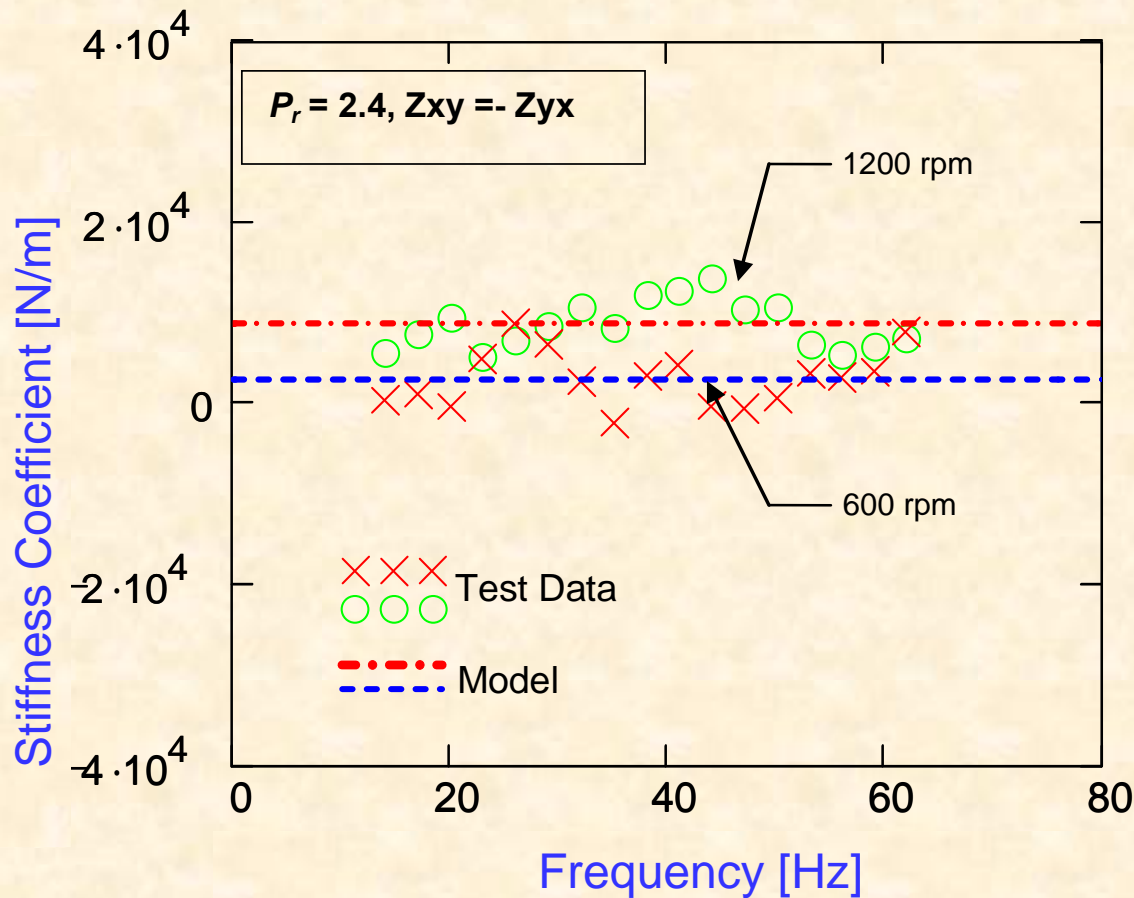


Predicted HBS stiffness (K_{sxx}) drops slightly in range from 20- 100 Hz. Tests show nearly constant K_{sxx}

Pressure ($P_r = P_s/P_d$) has negligible effect on seal direct stiffness, K_{sxx}

HBS predicted & test cross stiffness vs. frequency

Frequency 25-100 Hz



$$Z_{yx} = -Z_{xx} \frac{\bar{y}}{\bar{x}}$$

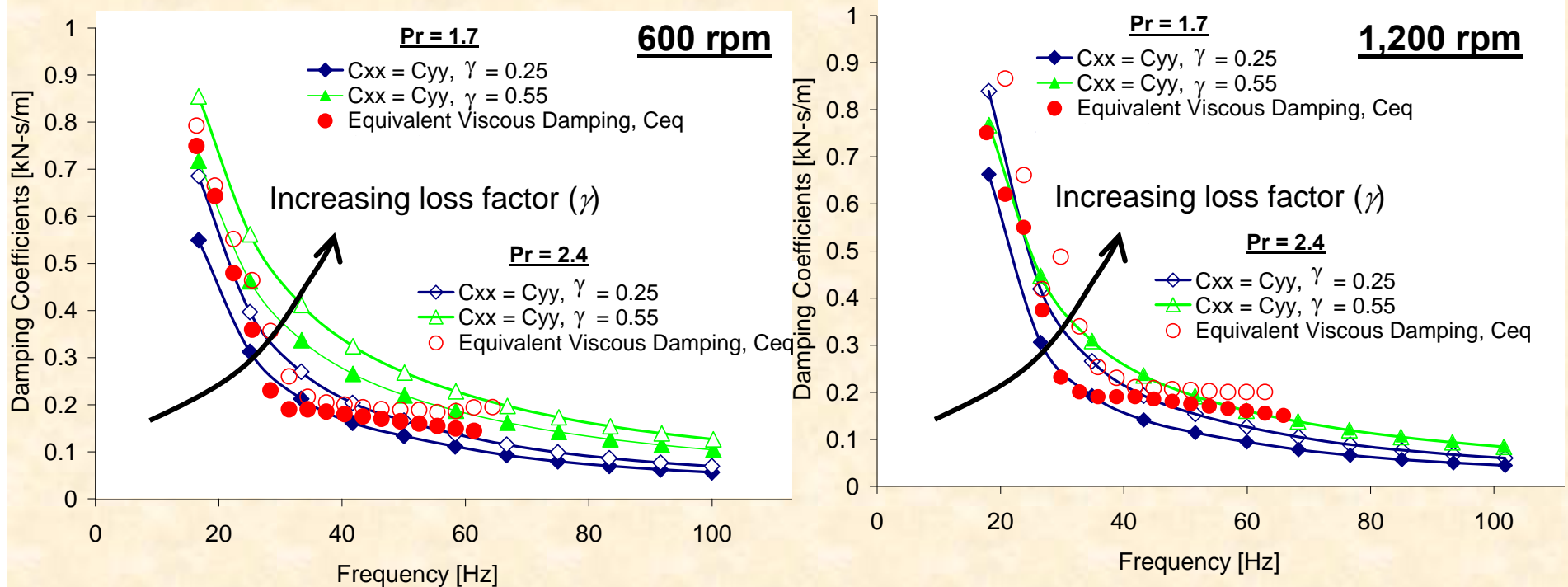
HBS cross stiffness
(K_{sxy}) \ll direct
stiffness (K_{sxx})

Pressure ($P_r = P_s/P_d$) has
negligible effect on seal
cross stiffness, K_{sxy}

HBS predicted & test damping vs. frequency

Frequency 25-100 Hz

Pressure ratio ($P_r = P_s/P_d$) = Discharge/Supply



HBS direct damping (C_{sxx}) decreases with excitation frequency. Loss factor coefficient (γ) models well seal structural (**hysteresis**) damping

Conclusions

- A structural loss factor (γ) and a dry friction coefficient (μ) effectively characterize the energy dissipation mechanism of a Hybrid Brush Seal (HBS).
- **HBS Direct stiffness ($K_{sxx} = K_{syy}$) decreases minimally with rotor increasing rotor speed for $P_r = 1.7$ and 2.4 HBS**
Cross-coupled stiffness ($K_{sxy} = -K_{syx}$) is much smaller than the direct stiffness coefficients.
- HBS Direct viscous damping coefficients decrease as a function of increasing excitation frequency.